



FCA and CNH Industrial  
Official Global Partners

**EXPO**  
MILANO 2015

# Model based design at CNHi

The transition to full model based implementations

Carlo Cloet – Karel Viaene, CNHi Zedelgem

MathWorks Benelux user's conference

June 11th, 2015

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## Key Takeaways

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- CNHi is adopting an end-to-end model-based development strategy
- Model based design is a key enabler for developing innovative functionalities

# CNH Industrial

## Our Products



Trucks



Buses



Firefighting Equipment



Civil Protection and Defence Vehicles



Skid Steer Loaders



Crawler Excavators



Engines and Transmissions



Tractors



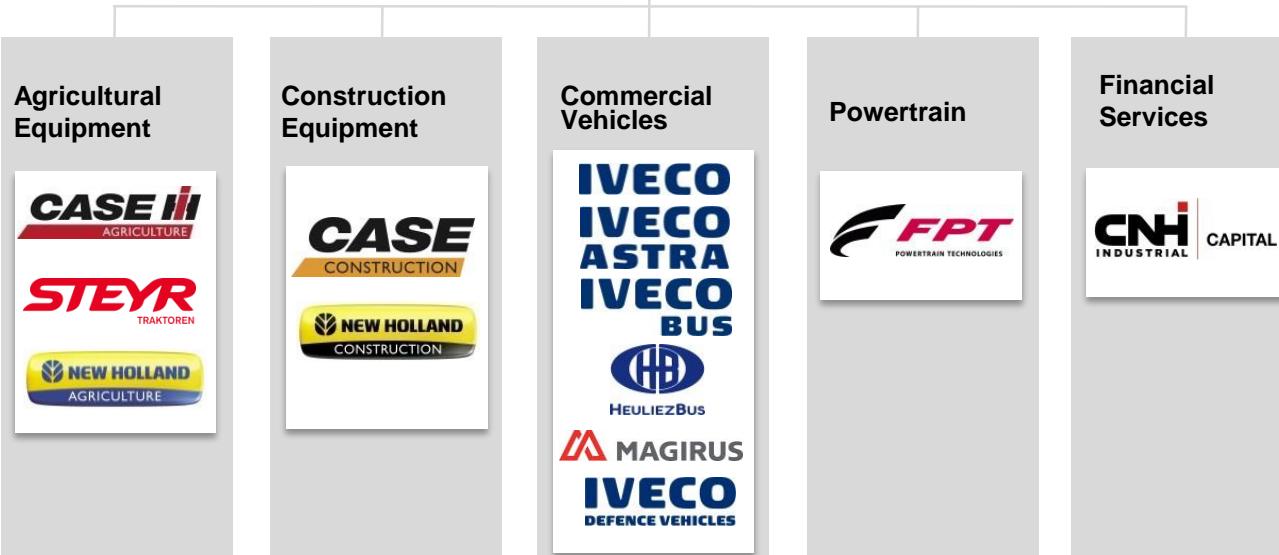
Combines

# CNH Industrial

## Company Structure



&



# CNH Industrial

Key Figures (31 Dec 2014)

1  
company

12  
brands

49  
R&D Centers

64  
plants

190  
national markets

69,207  
employees

6,100  
individuals dedicated to innovation

7,518  
active patents owned

\$ 1,106  
million invested in R&D

\$ 6  
million invested  
in training

\$ 708  
million net income

\$ 32,555  
million revenues

\$ 8,857  
million total  
available liquidity



# Model based design at CNHi (Zedelgem)

+10 years of model-based design experience



Forage harvester automated filling



Sugar Cane Harvester Drivetrain



Grape Harvester Drivetrain



Display Logic

Combine header height control  
Hydro-pneumatic suspension  
Feedrate control



Baler HIL Testing

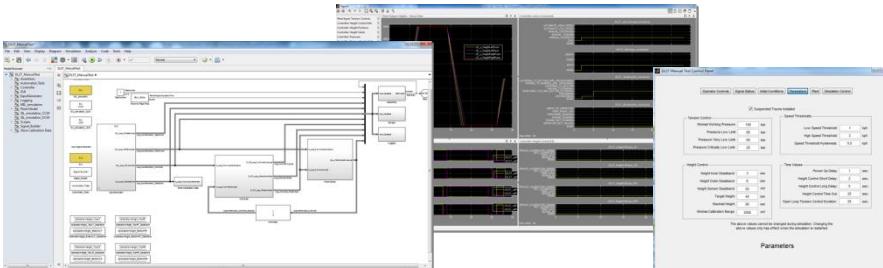


Baler application logic

# Innovation Challenges and Achievements

## Transitioning to a complete model-based implementation

- Objective: convert combine legacy C code to a full model-based implementation
  - Simplify transfer from innovation to product development
  - Avoid manual integration work
  - Consolidate legacy code base
  - Increase level of abstraction
  - Leverage MIL capability (test early, test often), rapid prototyping, etc



# How did we get there and leverage MathWorks?

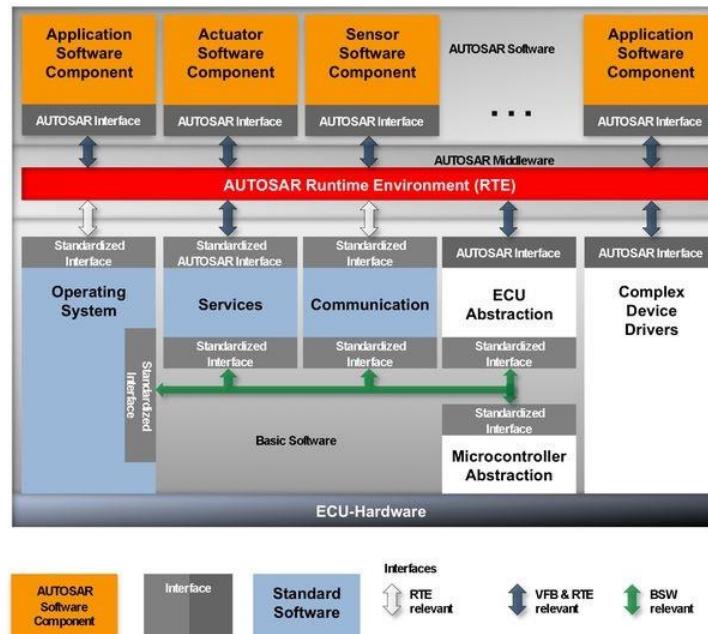
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- 3 major challenges:
  - System integration
  - Team based development
  - Functional implementation and validation

# How did we get there and leverage MathWorks?

## Challenge 1: System Integration

- How to integrate 100's of models into a functioning vehicle?
- Key enablers: AUTOSAR architecture + Simulink built-in AUTOSAR support

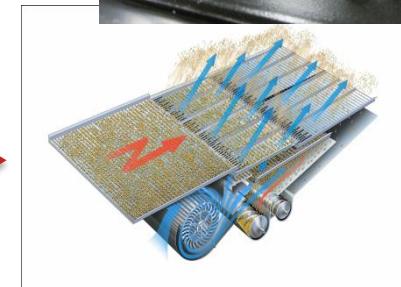
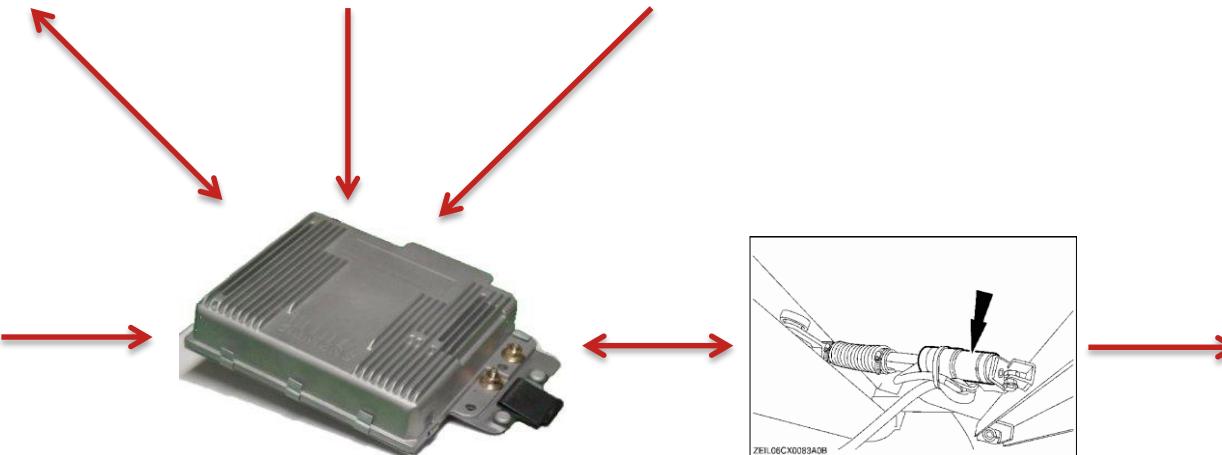
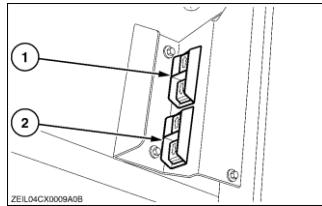
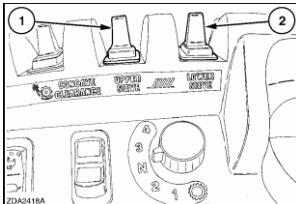
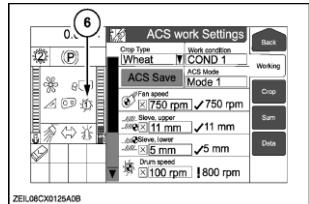


Source: <http://www.autosar.org/about/technical-overview/>

# How did we get there and leverage MathWorks?

## Challenge 1: System Integration

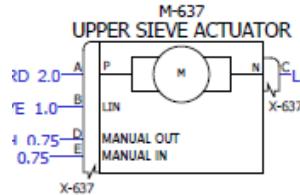
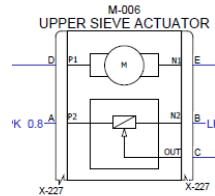
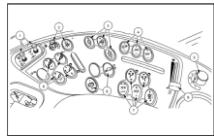
- Example subsystem: sieve control logic



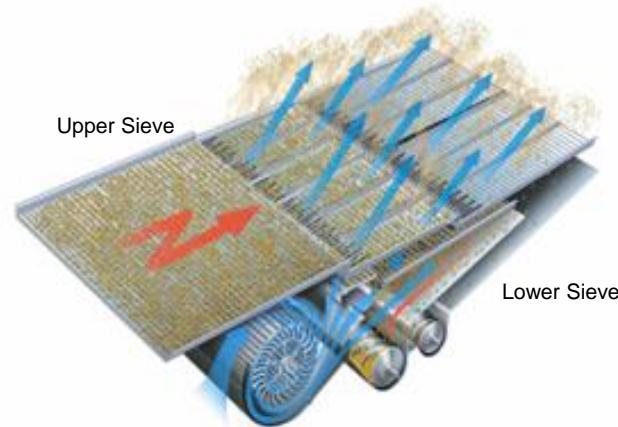
# How did we get there and leverage MathWorks?

## Challenge 1: System Integration

- Additional integration challenges



Same functionality,  
different hardware

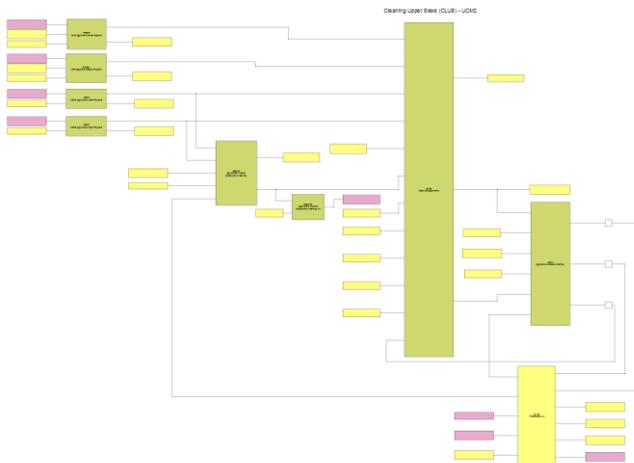


Same functionality,  
multiple instances

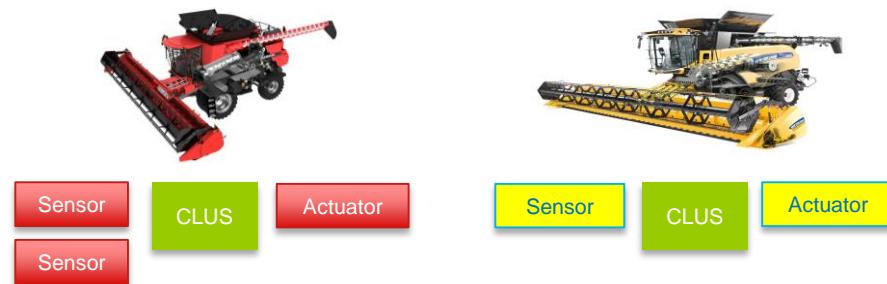
# How did we get there and leverage MathWorks?

## Challenge 1: System Integration

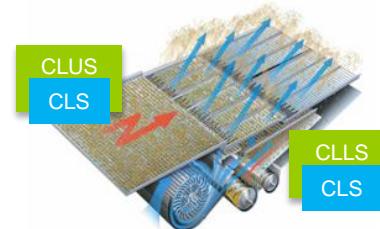
- Approach: component based architecture



Application SWCs  
Sensor SWCs  
Actuator SWCs



Application SWC re-use  
by use of engineering unit interfaces



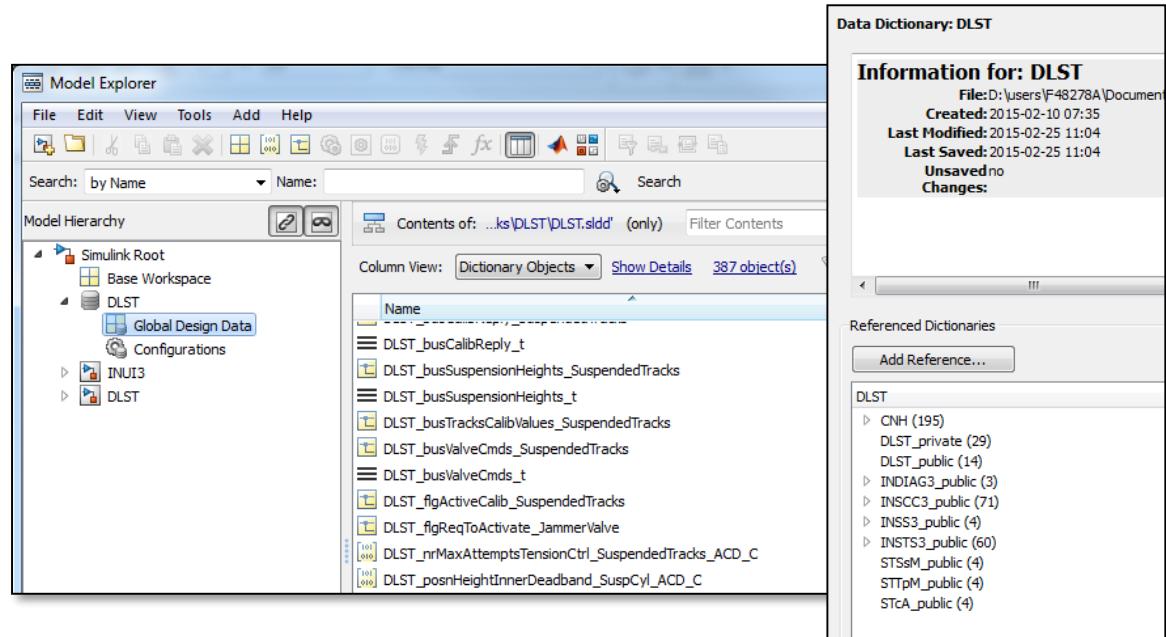
Multi-instance support  
via Simulink library implementation

CLS

# How did we get there and leverage MathWorks?

## Challenge 2: Team based development

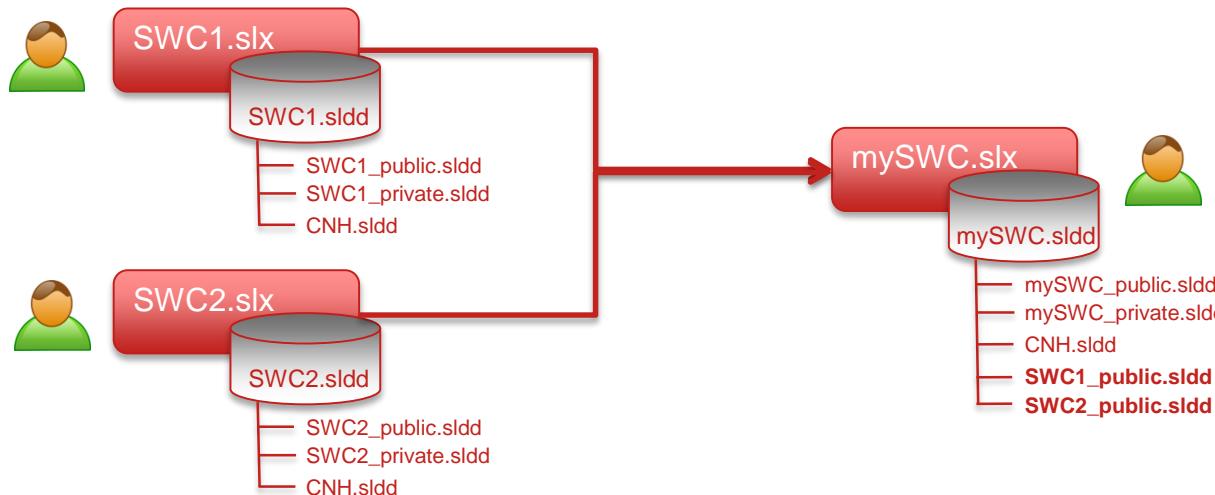
- How to enable concurrent model development by multiple people?
- Key enabler: Simulink data dictionary feature (introduced in R2014a)



# How did we get there and leverage MathWorks?

## Challenge 2: Team based development

- Using references to “public” data dictionaries to obtain input signal definitions
  - Public data dictionaries establish contracts among otherwise independent developers



# How did we get there and leverage MathWorks?

## Challenge 3: Functional implementation and validation

- Intellifill on Forage harvester
  - Forage harvester operation
  - Automated trailer filling
    - ✓ 3D camera
    - ✓ <https://www.youtube.com/watch?v=-zaQnygsMuQ>
  - Why automation
  - Challenges





## FR9000 IntelliFill™ System



# How did we get there and leverage MathWorks?

## Challenge 3: Functional implementation and validation

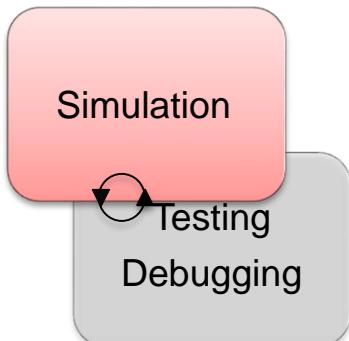
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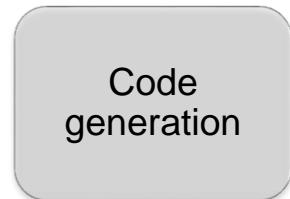
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## Challenge 3: Functional implementation and validation

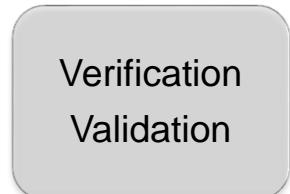
Development



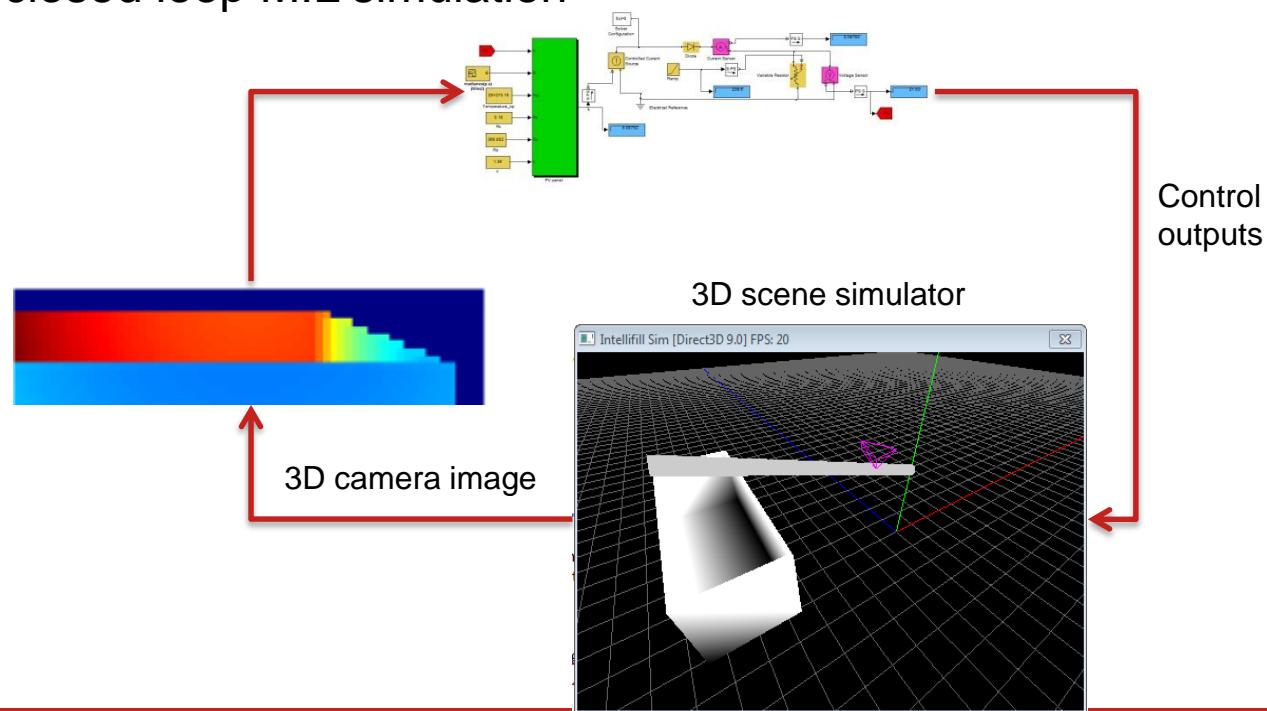
Integration

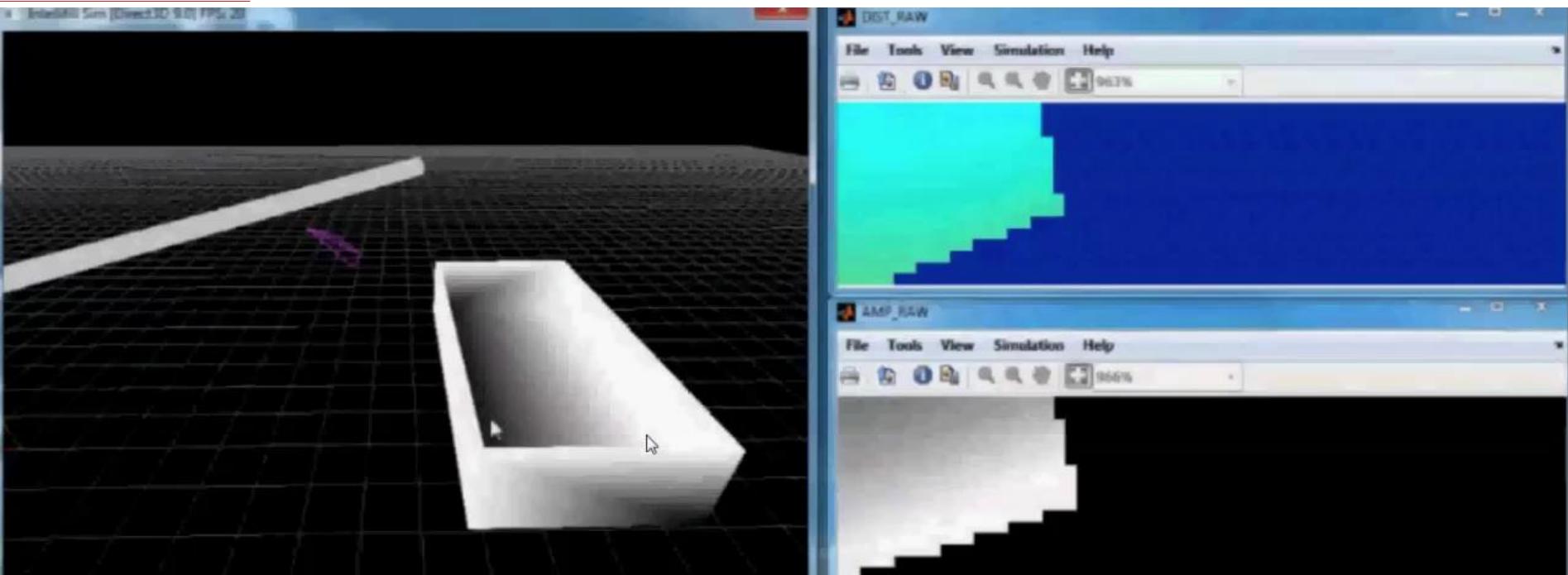


Validation



- Software architecture and algorithm development through closed loop MIL simulation

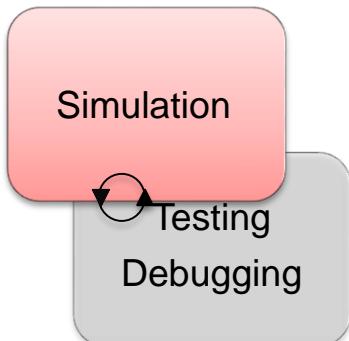




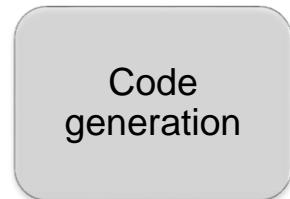
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## Challenge 3: Functional implementation and validation

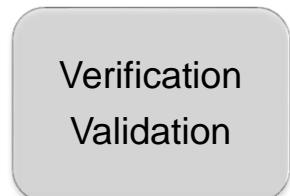
Development



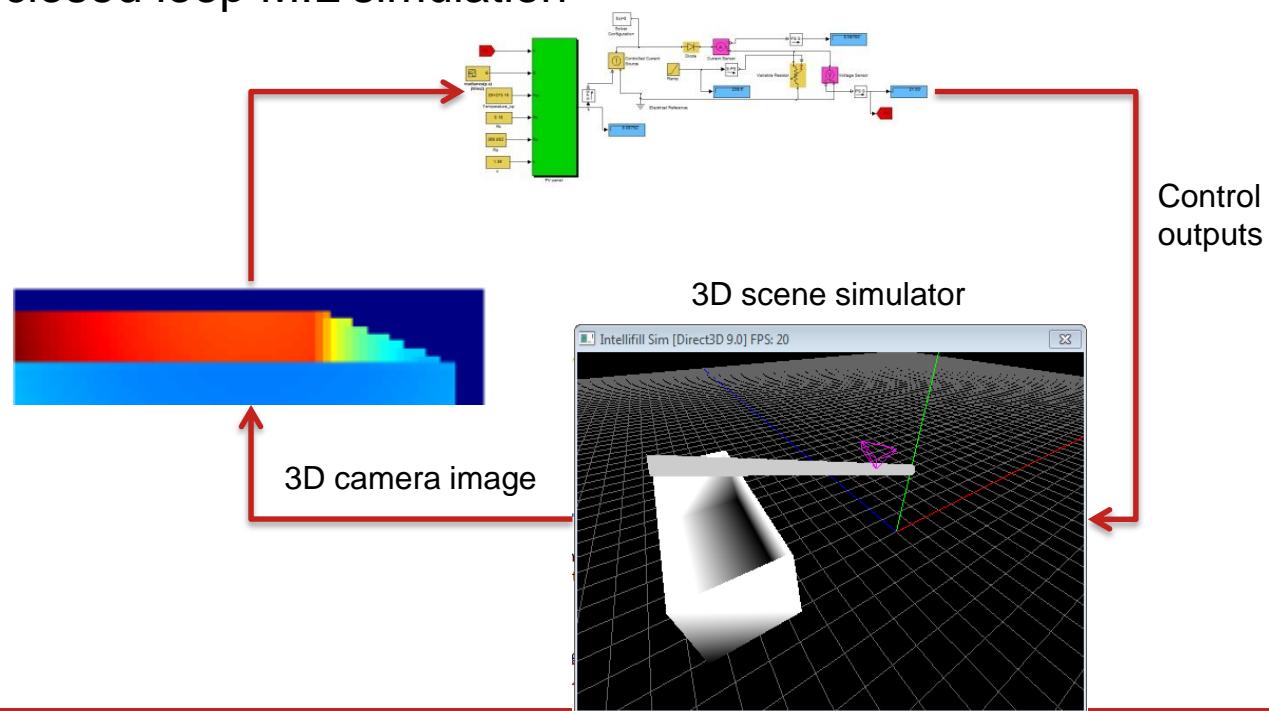
Integration



Validation



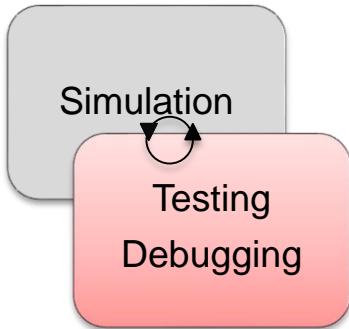
- Software architecture and algorithm development through closed loop MIL simulation



# How did we get there and leverage MathWorks?

## Challenge 3: Functional implementation and validation

Development



- On vehicle testing, debugging and fine-tuning in simulink environment



Integration

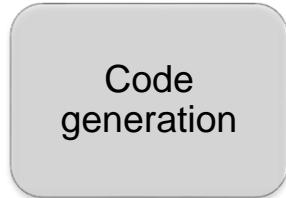
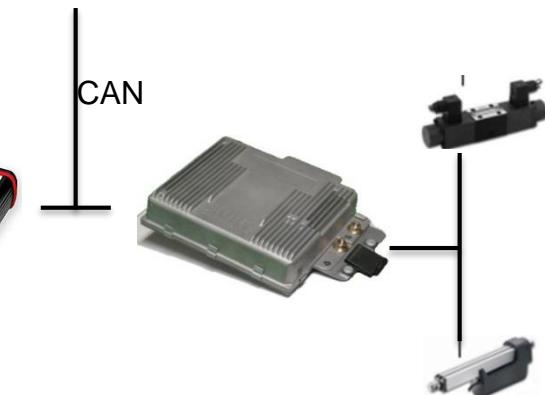
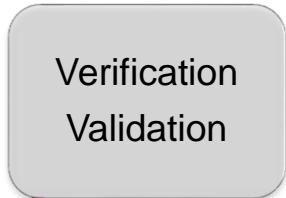


Image processing & controls



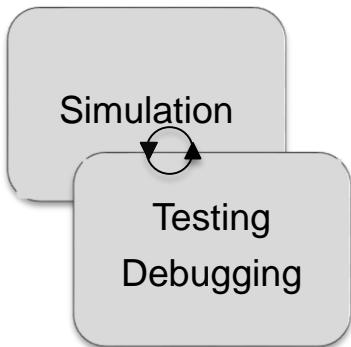
Validation



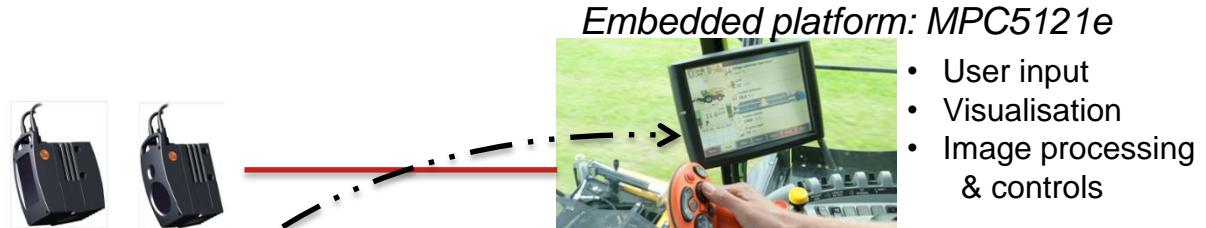
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## Challenge 3: Functional implementation and validation

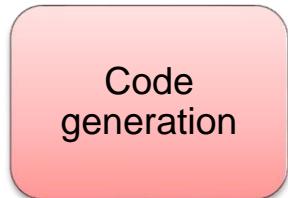
Development



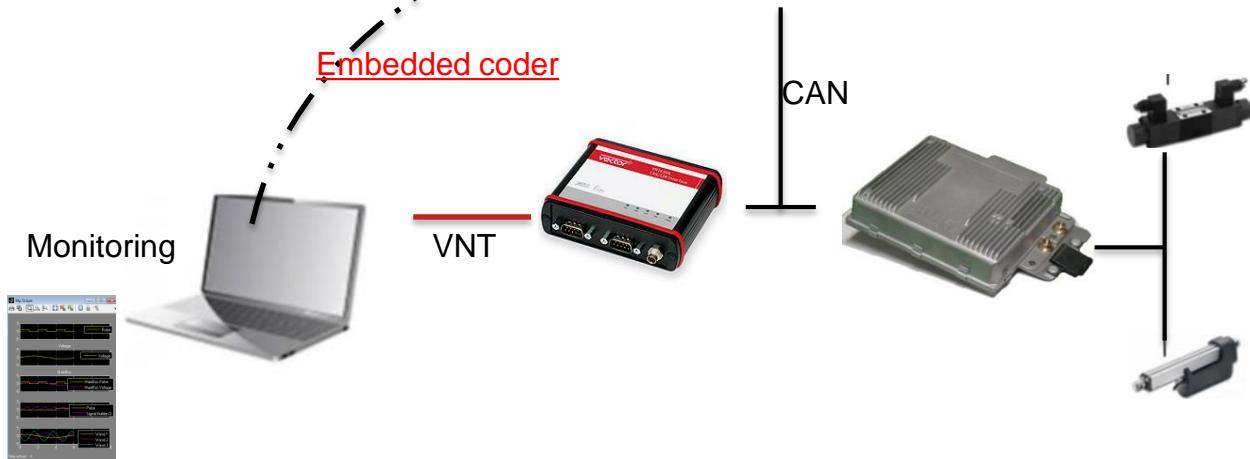
- Integration in Vehicle display controller with embedded coder



Integration



Validation



# Key Takeaways

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- CNHi is adopting an end-to-end model-based development strategy
  - Enabler 1: Simulink built-in AUTOSAR support
  - Enabler 2: Simulink datadictionary feature
- Model based design is a key enabler for developing innovative functionalities
  - Enabler 1: MIL simulation: Closed loop simulation with 3D scene simulator
  - Enabler 2: Rapid Prototyping: Instrument control toolbox & Vehicle network toolbox
  - Enabler 3: Code generation: Embedded coder allows fast integration